

**ICIO200  
ICIO205**

**DDC controllers**



**Summary**

DDC (Direct digital control) controller ICIO200 and ICIO205 are free programmable process stations with ARM Cortex M4 processor and OS FreeRTOS. They contain one Ethernet port, 8 AI, 8 DI, 6 AO and 8 DO. ICIO205 contains also a RS485 interface and 8 MB external RAM. ICIO200 is suitable for control of small installations (up to about 30 physical data points) compared to ICIO205 which is suitable for control of larger installations (approximately 150 physical data points).

**Application**

- Free programmable control units for HVAC systems and other applications with web access
- Data acquisition, processing, and presentation systems with advanced networking features
- Protocol converters with web data presentation (must be programmed by user)

**Function**

The controller hosts an embedded FreeRTOS operating system which boots up the Merbon runtime with the application. The board contains real time clock with battery backup, flash memory containing OS, runtime, application, and other data (time programs, setpoints etc.), and a watchdog. It is also possible to use NVRAM to backup parameters in case of unexpected system shutdown.

The application is created and uploaded in the Merbon IDE development environment. The maximum application program size depends on number of physical and software data points, amount of function blocks which require more memory (e.g. time schedulers), degree of code optimisation, and number of connections the PLC has to handle.

For communication with other devices, ICIO200 contains 1x Ethernet port. I/Os integrated on the board are 8 AI, 8 DI, 6 AO and 8 DO. The ICIO205 contains 1x Ethernet port and 1x RS485 interface for I/O module extension, with the same onboard I/O mix as the ICIO200.

Consider that ICIO200 is originally intended to control its own inputs and outputs. ICIO205 has sufficient computing power to control larger installation with external I/O modules and communication channels (for example Modbus TCP server, or SSCP client).

The process station contains a web server for remote connection and user intervention. The web pages are created in Merbon HMI editor, which is included in the package of development programs. The exported web definition is uploaded to the process station through Merbon IDE (see Web definition in PLC properties).

The module is 217 mm wide and mounts on a standard DIN rail.

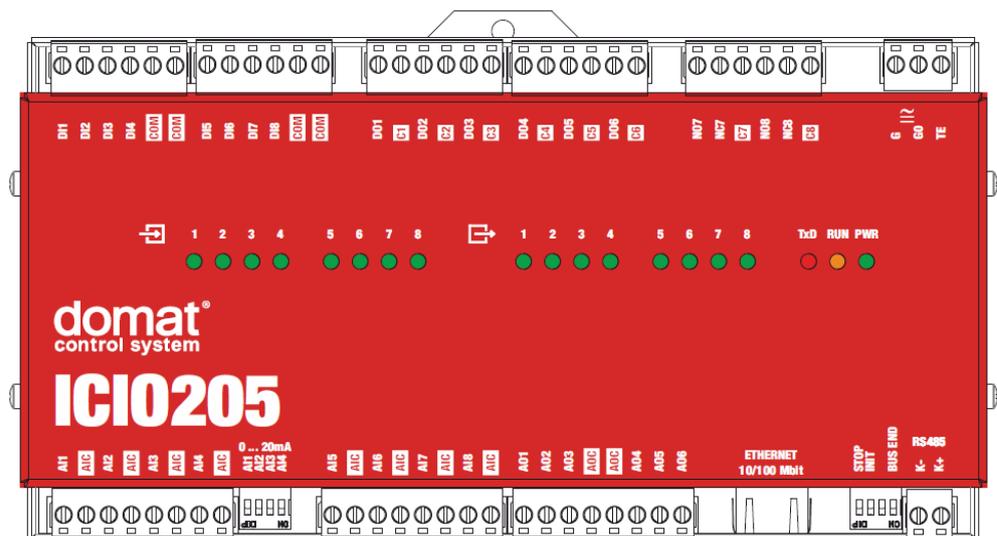
## Technical data

Power	24 V AC/DC $\pm$ 20 %; max 10 W
<b>Communication - ICIO200</b>	
Ethernet	1x Ethernet 10/100BaseT RJ45, 2 LED (link, data) integrated in the connector
<b>Communication - ICIO205</b>	
Ethernet	1x Ethernet 10/100BaseT RJ45, 2 LED (link, data) integrated in the connector
RS485	COM1 RS485 (K+, K-) galvanically insulated, insulating voltage 1 kV 300 ... 115 200 bit/s, parity and bits are set in SW maximal bus length 1200 m maximum number of modules depends on requested response time – up to 255 addresses, for common HVAC applications with ICIO205 use about 150 physical data points on the bus
19x LED	RUN, TxD, PWR, 8x DI state, 8x DO state
<b>Analogue inputs</b>	
Number	8
Resistance measuring range	0...1600 Ohm, 0...5000 Ohm, Pt100, Pt500, Pt1000, Ni1000-5000, Ni1000-6180 sensors (type of measuring is set through Merbon IDE, transformation is done in the runtime application)
Voltage measuring range	0...10 V DC (type of measuring is set through Merbon IDE)

Current measuring range	0...20 mA AI1 ... AI4: particular DIP switch must be in position ON (type of measuring is set through Merbon IDE) AI5 ... AI8: with an external resistor of 125 Ohm (parallel connection; type of measuring is set through Merbon IDE)
Resolution	16 bit
Galvanic insulation	Optically insulated up to 1 kV.
<b>Analogue outputs</b>	
Number	6
Voltage range	0...10 V DC
Analogue outputs load	min. 10 k $\Omega$ outputs are protected against permanent short-circuit – 10 mA limitation
Galvanic insulation	Optically insulated up to 1 kV.
<b>Digital inputs</b>	
Number	8
Voltage	24 V AC/DC – voltage must be applied (no dry contacts), e.g. from G and G0
Input current	4 mA
Maximum voltage	60 V DC, 40 V AC
Galvanic insulation	Optically insulated up to 1 kV.
<b>Digital outputs</b>	
Number	6 NO (normally open) relays (no voltage - open) 2 changing relays
NO relay load	3 A at 250 V AC, 750 VA 3 A at 30 V DC, 90 W
Changing relay load	8 A at 250 V AC, 2000 VA 8 A at 24 V DC, 192 W
Galvanic insulation	Optically insulated up to 1 kV.
Standard type	AC1, non-inductive load EN 60947-4-1
HW ICIO200	ARM Cortex M4 168 MHz, 10 MB FLASH, 256 KB SRAM, 4 KB NVRAM
HW ICIO205	ARM Cortex M4 168 MHz, 10 MB FLASH, 256 KB + 8 MB SRAM, 4 KB + 64 KB NVRAM

SW	Merbon IDE (supported from version ER2 2.2.0.0) Merbon HMI
Housing	Steel, powder coated surface
Dimensions	217 x 115 x 40 mm (including terminals); See the schema below.
Protection degree	IP20 (EN 60529)
Terminals	screw terminals M3, maximum wire cross-section 2,5 mm <sup>2</sup>
Ambient conditions	5 – 40 °C; 5 – 85 % relative humidity; non-condensing gases and chemically non-aggressive conditions (according to EN 60721-3-3 climatic class 3K3)
Standards regarding conformity	EMC EN 61000-6-2 ed.3:2005, EN 55022 ed.3:2010 EN 60950-1 ed.2:2006 + A11:2009 + A12:2011 + A1:2010 + A2:2014 EN 50581:2012
EU legislation	Council Directive 2006/95/EC, health and low voltage equipment safety  Council Directive 2004/108/EC, electromagnetic compatibility  Council Directive 2011/65/EC, certain hazardous substances in electrical and electronic equipment

## Terminals



**Terminals and connectors:**

<b>DI1 ... 8</b>	digital inputs 1 ... 8
<b>COM</b>	ground (common)
<b>DO1 ... DO6</b>	relay output 1 ... 6, normally open against C1 ... C6
<b>C1 ... C6</b>	relay output 1 ... 6, ground
<b>NO7</b>	relay output 7, normally open against C7
<b>NC7</b>	relay output 7, normally closed against C7
<b>C7</b>	relay output 7, ground
<b>NO8</b>	relay output 8, normally open against C8
<b>NC8</b>	relay output 8, normally closed against C8
<b>C8</b>	relay output 8, ground
<b>G</b>	power
<b>G0</b>	power
<b>TE</b>	optional connection for shielding

<b>AI1 ... 8</b>	analogue inputs 1 ... 8
<b>AIC</b>	<b>analogue input ground</b> (common) Notice: All analogue inputs AI1 to AI8 have common ground AIC. The inputs are optically separated from the other parts of the I/O module. For three-wire connection (active sensors, e.g. pressure, humidity), the analogue input ground AIC must be connected with the peripheral 24 V AC power ground. As all I/O types are mutually separated in the module, it is possible to use one common transformer to power both the active peripherals and the ICIO module

<b>AO1 ... 6</b>	analogue outputs 1 ... 6
<b>AOC</b>	<b>analogue output ground</b> (common) Notice: The ground is optically separated from the other parts of the I/O module. For three-wire connection (active periphery, e.g. valves actuators, frequency changer), the analogue output ground AOC must be connected with the peripheral 24 V AC power ground. As all I/O types are mutually separated in the module, it is possible to use one common transformer to power both the active peripherals and the ICIO module.

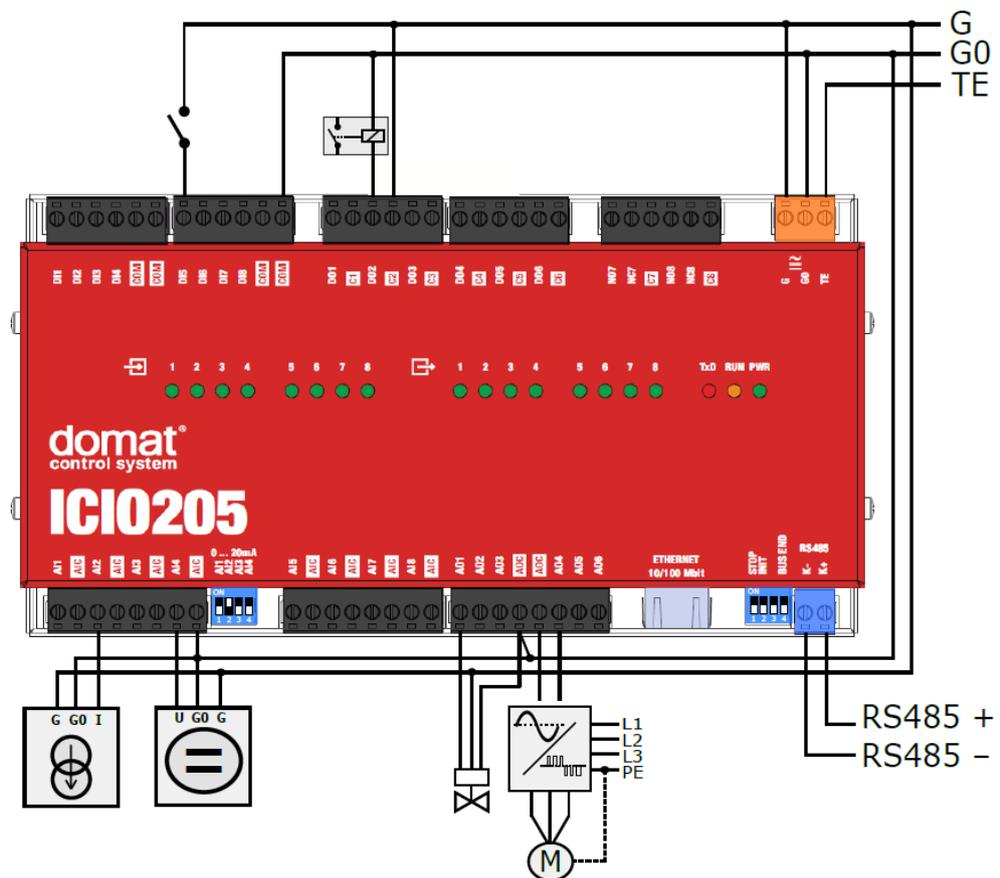
<b>Ethernet</b>	network interface
<b>RS485</b>	port COM1 – serial line RS485, terminals K+, K- ( <b>ICIO205 only</b> )

**LED indication:**

<b>LED DI1...8</b>	Indication the statuses of the inputs (ON: voltage 24 AC/DC $\pm 10\%$ ; OFF: no or low voltage)
<b>LED DO1...8</b>	Indication the statuses of the outputs (ON: relay closed; OFF: relay open)
<b>TxD</b>	red LED – M-bus transmitting data at COM1 (flashing: receiving data; still ON: shortcircuited bus or bus overload)

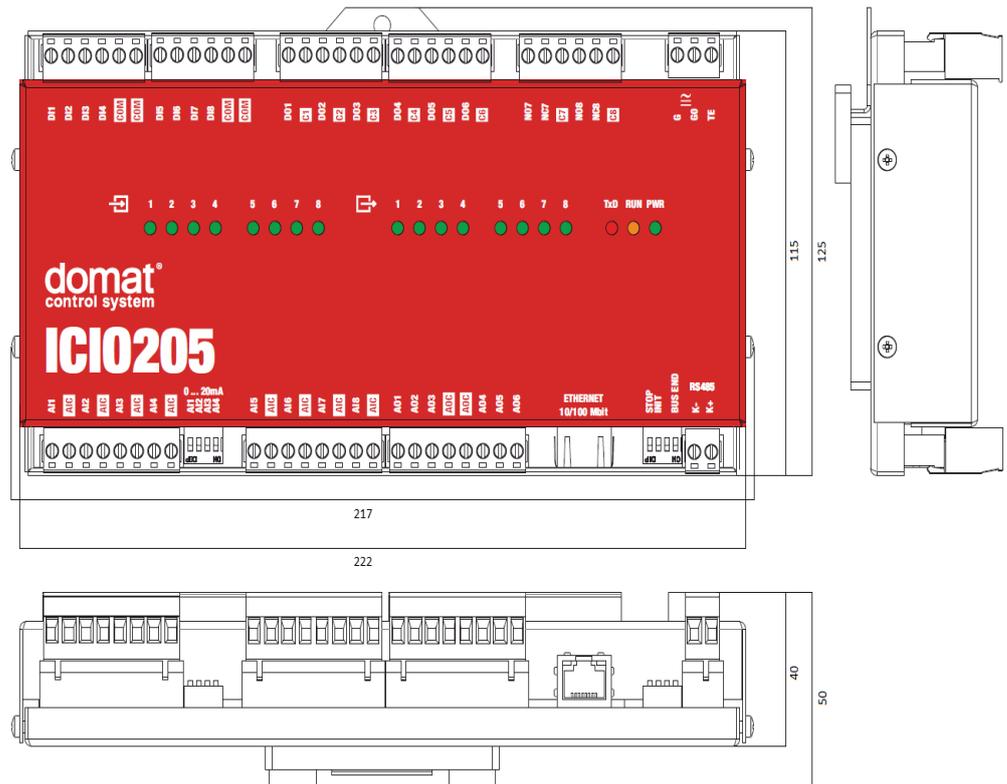
<b>RUN</b>	yellow LED – system cycle (OK: LED flashes periodically 1 s ON, 1 s OFF; ERROR: LED flashes in other pattern, LED is permanently ON or OFF)
<b>PWR</b>	green LED – power (ON: power OK; OFF: no power applied, weak or damaged power supply, ...)
<b>DIP switches:</b>	
<b>STOP</b>	if ON, the runtime is running, program execution is stopped
<b>INIT</b>	if ON at power-up, configuration parameters are brought to defaults (see Configuration parameters in Merbon IDE; e.g. IP address, user and password, database settings, proxy, ... )
<b>BUS END</b>	if ON = bus end RS485; the first and last devices on bus should have bus end ON ( <b>ICIO205 only</b> )
<b>AI1 ... 4</b>	if ON, the parallel resistance 125 Ohm is connected and input is ready for current measuring

## Connection



Resistive (passive) sensors are connected between AIx and AIC terminals, for the first 4 inputs must be DIP switch 0 ... 20 mA in the off position. The resistance range is set in the software.

## Dimensions



Dimensions are in *mm*.

## Programming

### Merbon IDE

The main programming tool is the Merbon package which contains I/O editor, graphical editor of the function plan (FBD), structure text editor and compiler (Merbon IDE). The Merbon package contains also LCD menu editor as well as web editor (Merbon HMI).

The application program consists of function blocks which are stored in libraries. Those contain analogue and digital functions, mathematical blocks including goniometric functions, time schedulers, alarm blocks, and HVAC specific blocks (heat recovery, dewpoint calculation, enthalpy, pump switch etc.). The program can be set up also as structure text (ST) or with combination of both types of programming languages.

## Communication

Default network settings are:

IP address	192.168.1.10
subnet mask	255.255.255.0
default gateway	192.168.1.1

SSCP user: admin

Password: rw

Notice: Do not forget to record the new network settings after change!

After these values have been changed, it is possible to bring the process station into default settings by the INIT DIP switch: set INIT to ON and restart the station. All

values in the PLC configuration are set to defaults. The PLC will respond at the default IP address and it is possible to change the old address through Merbon IDE.

The controllers can share variables over the Ethernet network (outside temperature, heat demands etc.) together with other PLC platforms.

The runtime provides drivers for communication with subsystems. For example Merbon runtime contains: Modbus TCP / RTU (server/client), M-Bus, IEC62056-21, SSCP, and SoftPLC link. The complete list of drivers can be found in the Channel configuration dialogue in the most recent Merbon release. Please check the required protocol features and functions with the list of implemented features in the Merbon IDE help. It is also possible to program own communication drivers using the I/O library functions in structure text language.

**Number of communication channels** (on the serial lines and Ethernet) to I/O modules and subsystems is not directly restricted. It depends on available RAM PLC memory.

**Number of connections from SSCP clients is max. 5.** This includes connections from RcWare Vision, Merbon IDE, HT102/200, mobile application Merbon Menu Reader, connection from other PLCs over SSCP etc.

**Number of connections from Modbus TCP clients on Modbus TCP server is max. 5.**

Other clients channels (web, ...) are not directly restricted.

#### **RoHS notice**

The device contains a non-rechargeable battery which backups the real-time clock and part of the memory. After the device is not operable, please return it to the manufacturer or dispose of it in compliance with local regulations.

#### **Safety note**

The device is designed for monitoring and control of heating, ventilation, and air conditioning systems. It must not be used for protection of persons against health risks or death, as a safety element, or in applications where its failure could lead to physical or property damage or environmental damage. All risks related to device operation must be considered together with design, installation, and operation of the entire control system which the device is part of.

**Changes in  
versions**

07/2016 – First version.

07/2017 – Added terminals connection scheme.

11/2017 – Added safety note, passive sensor connection information and power tolerance.